

Compact Hydraulic System for Energy Savings and High Precision

# **POWER Meister**

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## **Compact Hydraulic System for**

## **Energy Savings and High Precision**

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The AC servo motor controls rotational speed and direction of the pump. The pump generates flow and pressure to match the operating cycle of machinery and stops during idle times.

Incredible energy savings are achieved by operating only when necessary. Position, Speed and Pressure are controlled with great precision by using a high-speed digital processing servo controller.





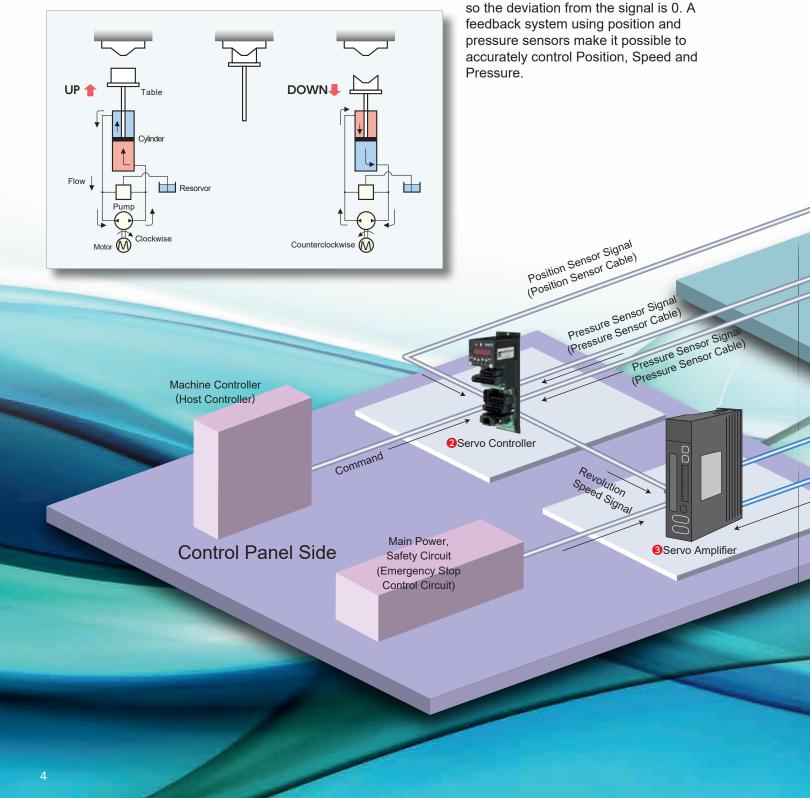
# Precision Control of Position, Speed and Pressure by Our Original Feedback System

#### Principle of Operation

Rotating the motor clockwise brings hydraulic fluid to the head-side of the cylinder which lifts the table. Reversing the motor brings hydraulic fluid to the rod-side and pushes the cylinder down. The rotational direction of the pump controls the direction of the cylinder.

### System Configuration (Standard)

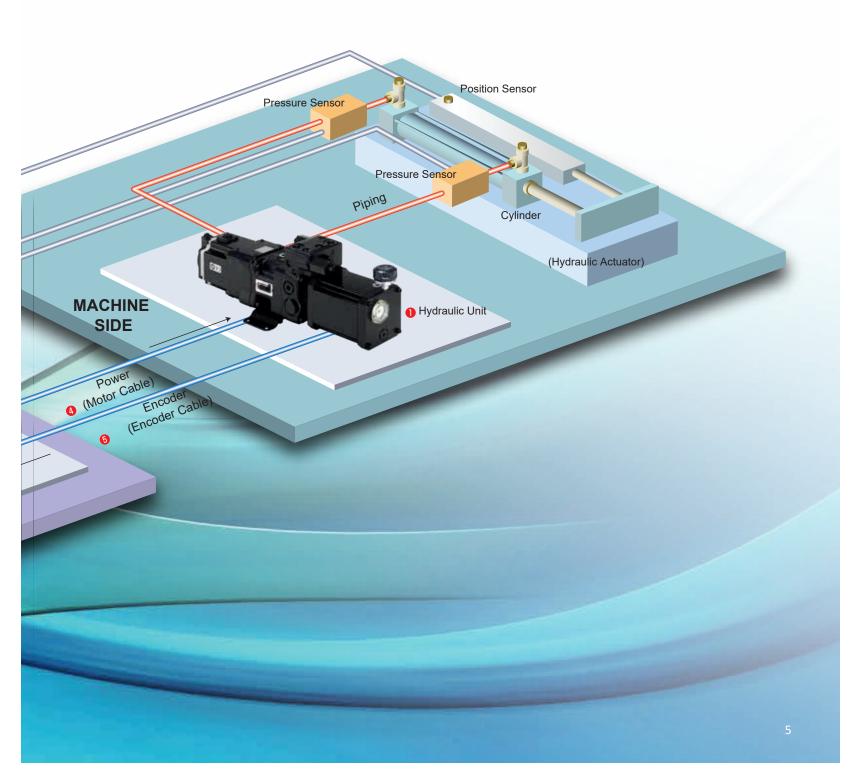
The hydraulic unit responds to signals to operate the cylinder (position, speed and pressure) that are sent from the Machine Controller to the Servo Controller. The Servo Controller receives feedback from sensors and accurately controls the cylinder so the deviation from the signal is 0. A feedback system using position and pressure sensors make it possible to accurately control Position, Speed and Pressure



#### **Power Meister Component Device**

- Hydraulic Unit (UPS)
- 2 Servo Controller (EPD)
- 3 Servo Amplifier (For AC motor of 1)
- **4** Motor Cable (3m, 5m or 10m) (10, 16 or 32 feet)
- **5** Encoder Cable (3m, 5m or 10m) (10, 16 or 32 feet)
- Motor Fan Cable (choose from 3m, 5m, and 10m) used for UPS-1A: 11kW and UPS-2A: 20kW motor only.

Piping, wiring, hydraulic cylinder, sensor and control panel to be supplied by customer. (Please contact us about cylinders and sensors.)

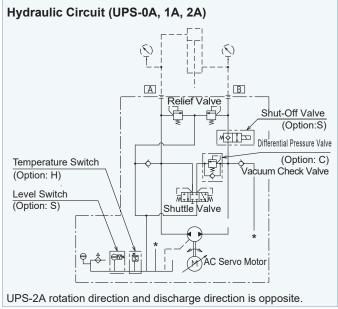


#### Hydraulic Unit (UPS)

#### **Space-Saving Design**

In-line AC servo motor, hydraulic pump and reservoir. Relief valve and other valves are included in base unit. A port is discharge port when pump rotates counter-clockwise (viewed from AC servo motor). B port is discharge port when pump rotates clockwise. Piping are only between A&B ports of unit and ports of cylinder. Due to rotation of AC servo motor, cylinder can be extended or retracted.

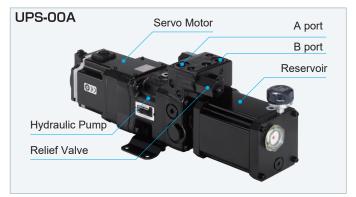


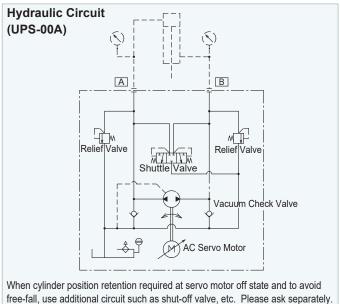


#### **Options**

Additional options that improve usability of UPS:Differential pressure valves that cancel pressure imbalance and shut-off valve to prevent free-fall when motor power turned off are available as UPS options for self-load generation circuit. Temperature switch for abnormal oil temperature detection and float switch for abnormal oil level detection are also available.

Note) No differential pressure valve, shut-off valve, temperature switch, level switch option for UPS-00A. No shut-off valve, temperature switch, or level switch option for UPS-2A.

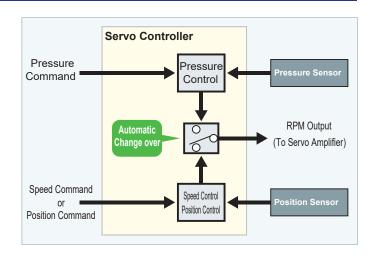




#### Servo Controller (EPD)

#### Easy and Precise Control by High-Speed Calculation

Position sensor and pressure sensor feedback signals. According to cylinder load, servo controller commands to servo amplifier with calculating direction of rotation and rotation speed. Through high-speed calculation of servo controller, it is possible to operate cylinder easily and precisely with command and feedback control. The servo controller features an automatic changeover control mode function as standard. In accordance with actual load conditions, speed control and pressure control or position control and pressure control are automatically selected. Therefore, it is not necessary to control timing by changing the control modes with the host controller, and changing from speed control to pressurizing control can be done smoothly. This function can realize pressurizing control that does not generate surge pressure at the time of changeover. Contact signals from the host controller can also change the control modes.

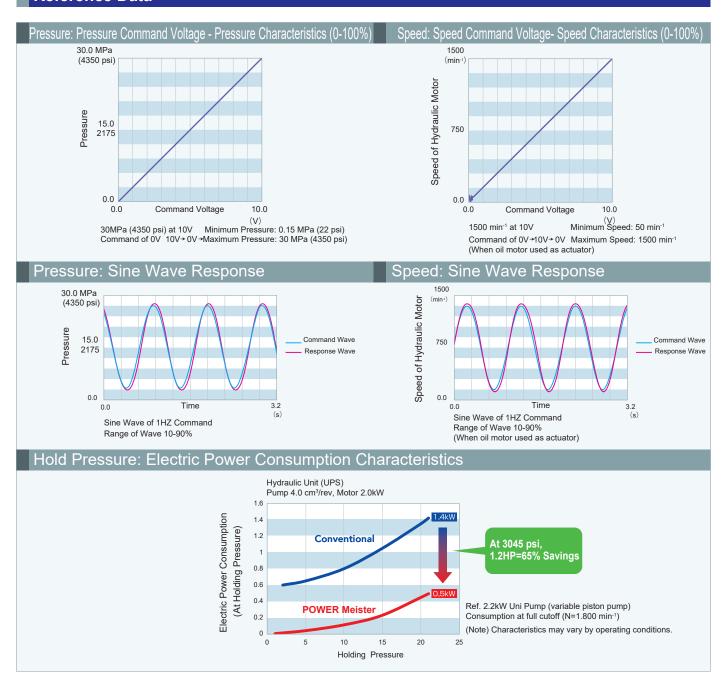


#### Servo Amplifier (EPA)

Use a servo amplifier compatible for the servo motor installed in HPU.

The servo amplifier will activate servo motor to drive the pump according to the rpm command from servo controller.

#### **Reference Data**



#### **Application Examples and Results**

Metal forming Machines	Compact machine space, precise measures to manufacture.
Caulking Machines and Press Fitting Machines	Control power and position of caulking to maintain quality control. Conventional positioning mechanism not needed.  Eliminates the inconsistency of work done by hand.
Grinding Machines	Precise position of start to grind, energy saving to maintain constant pressure for long periods.
Precision Press Machines	Smooth change from high speed to process without surge pressure, for improved quality of products. Less cycle time.
Straightening Machines	Energy saving, low noise, reduced fluid, space saving by integrating unit into machine. Less logistics cost.
Other Applications	Other applications include those requiring compact machines, and high load machines which are incapable of using ball screws.

## Hydraulic Unit Specifications

Electric Motor	AC servo motor (0.75~20kW, driven by servo amplifier) (1.0~26.8HP)  Power voltage Three-phase AC200~2 30V 50/60Hz (Servo Amplifier Power)  Fan motor power: Single phase: AC200~230V 50/60Hz required.  (UPS-1A: 11kW, UPS-2A: 20kW only)
Piston Pump	(2.0~35.0 cm³/rev) (0.12~2.13 in³/rev)
Ambient Temperature/Humidity	0~+40°C (32~104°F) / 20~90% RH
Fluid Temperature	5~60°C (41~140°F) (Note 6)
Recommended Fluid	UPS-00A, 01A, 1A: ISO VG32~68 (VG 46 recommended), UPS-2A: ISO VG 46 only
Range of Viscosity	20~200mm²/s {cSt}
Cleanliness Level	NAS class 10 (ISO 18/16/13)
Setting Range of Relief Valve	UPS-00A:3.5~32MPa UPS-0A/1A/2A:3.5~
Maximum Pressure	30MPa (4350 psi) (Note 7) (Maximum working pressure varied by motor capacity and/or optional features.)
Color	Black

#### **UPS-00A**

Model	Motor Output kW (HP)	Volume cm³/rev (in³/rev)	Max Rotational Speed min <sup>-1</sup> (Note 1)	Max Flow &/min(Note 2) (GPM)	Rated Pressure Cont. MPa (Note 3)(psi)	Max Working Pressure Short Time MPa(Note 3) (psi)	Reservoir Lit. (Gallon)	Allowable Flow Change Lit. (Gallon(Note 4))
UPS-00A-2*07	0.75(1.0)	2.0(0.12)	3000	6.0(1.59)	6.4 (914)	9.6(1371)	V:0.75(0.20)	1/0 0/0 1/1
UPS-00A-2*10	1.0(1.3)	2.0(0.12)	3000	6.0(1.59)	8.5(1214)	12.7(1814)	H:0.65(0.17)	V:0.3(0.11)
UPS-00A-3*10	1.0(1.5)	3.0(0.18)	3000	9.0(2.38)	5.7 (814)	8.5(1214)	L:Tankless(Note-5)	H:0.2(0.05)

#### **UPS-0A**

Model	Motor Output kW (HP)	Volume cm³/rev (in³/rev)	Max Rotational Speed min <sup>-1</sup> (Note 1)	Max Flow &/min(Note 2) (GPM)	Rated Pressure Cont. MPa (Note 3)(psi)	Max Working Pressure Short Time MPa(Note 3) (psi)	Reservoir Lit. (Gallon)	Allowable Flow Change Lit. (Gallon(Note 4))
UPS-0A-2*12	1.2(1.6)	2.0(0.12)	3000	6.0(1.59)	15.2(2171)	22.8(3257)		
UPS-0A-4*12	1.2(1.0)	4.0(0.24)	3000	12.0(3.17)	7.6(1086)	11.4(1629)	V:1.9(.50)	V:0.6(0.15)
UPS-0A-2*20	2.0(2.7)	2.0(0.12)	3000	6.0(1.59)	25.4(3629)	30.0(4350)	H:1.5(.40)	H:0.3(0.11)
UPS-0A-4*20		4.0(0.24)		12.0(3.17)	12.7(1814)	19.0(2755)		

#### **UPS-1A**

Model	Motor Output kW (HP)	Volume cm³/rev (in³/rev)	Max Rotational Speed min <sup>-1</sup> (Note 1)	Max Flow &/min(Note 2) (GPM)	Rated Pressure Cont. MPa (Note 3)(psi)	Max Working Pressure Short Time MPa(Note 3) (psi	Reservoir Lit. (Gallon)	Allowable Flow Change Lit. (Gallon(Note 4))
UPS-1A-5*35		4.7(0.29)		11.8(3.12)	21.1(3014)	30.0(4350)		
UPS-1A-7*35		6.7(0.41)		16.8(4.44)	14.8(2114)	22.2(3171)		
UPS-1A-9*35	0.5(4.7)	9.0(0.55)	0500	22.5(5.94)	11.7(1671)	17.5(2500)		
UPS-1A-11*35	3.5(4.7)	11.0(0.67)	27.5(7.28)	9.6(1371)	14.3(2073)			
UPS-1A-13*35		12.9(0.79)		32.3(8.53)	8.2(1171)	12.2(1769)		
UPS-1A-16*35		15.8(0.96)		39.5(10.45)	6.7(957)	10.0(1450)		
UPS-1A-5*45		4.7(0.29)		11.8(3.12)	30.0(4350)	30.0(4350)		Reservoir: -
UPS-1A-7*45		6.7(0.41)		16.8(4.44)	22.6(3229)	30.0(4350)		V:1.2(0.32),
UPS-1A-9*45	4.5(6.0)	9.0(0.55)	2500	22.5(5.94)	17.8(2543)	26.8(3829)	-: 4.5(1.20)	H:0.6(0.16)
UPS-1A-11*45	4.5(0.0)	11.0(0.67)	2500	27.5(7.28)	14.6(2117)	21.9(3129)	A:3.0(0.79)	Reservoir:A
UPS-1A-13*45		12.9(0.79)		32.3(8.53)	12.4(1798)	18.7(2711)	B:6.0(1.59)	V:0.6(0.16), H:0.4(0.11)
UPS-1A-16*45		15.8(0.96)		39.5(10.45)	10.2(1457)	15.2(2204)		11.0.4(0.11)
UPS-1A-7*55		6.7(0.41)		16.8(4.44)	27.9(3986)	30.0(4350)		Reservoir:B
UPS-1A-9*55		9.0(0.55)		22.5(5.94)	22.0(3143)	30.0(4350)		V:2.8(0.74), H:0.8(0.21)
UPS-1A-11*55	5.5(7.4)	11.0(0.67)	2500	27.5(7.28)	18.0(2571)	27.0(3857)		111010(0121)
UPS-1A-13*55		12.9(0.79)		32.3(8.53)	15.3(2219)	23.0(3286)		
UPS-1A-16*55		15.8(0.96)		39.5(10.45)	12.5(1873)	18.8(2686)		
UPS-1A-9*75		9.0(0.55)		22.5(5.94)	30.0(4350)	30.0(4350)		
UPS-1A-11*75	7.5(10.0)	11.0(0.67)	2500	27.5(7.28)	24.7(3529)	30.0(4350)		
UPS-1A-13*75	7.5(10.0)	12.9(0.79)	2500	32.3(8.53)	21.0(3045)	30.0(4350)		
UPS-1A-16*75		15.8(0.96)		39.5(10.45)	17.2(2457)	25.8(3686)		
UPS-1A-13*11K	11.0(11.7)	12.9(0.79)	0500	32.3(8.53)	30.0(4350)	30.0(4350)		
UPS-1A-16*11K	11.0(14.7)	15.8(0.96)	2500	39.5(10.45)	25.1(3586)	30.0(4350)		

#### **UPS-2A**

Model	Motor Output kW (HP)	Volume cm³/rev (in³/rev)	Max Rotational Speed min <sup>-1</sup> (Note 1)	Max Flow $\ell/\min_{(Note \ 2)}$ (GPM)	Rated Pressure Cont. MPa (Note 3)(psi)	Max Working Pressure Short Time MPa(Note 3) (psi)	Reservoir Lit. (Gallon)	Allowable Flow Change Lit. (Gallon(Note 4))
UPS-2A-25*11K		25.0 (1.52)		50.0 (13.2)	14.1 (2044)	21.1 (3060)		
UPS-2A-32*11K	11.0 (14.75)	32.0 (1.95)	2000	64.0 (16.9)	11.7 (1696)	17.5 (2537)		
UPS-2A-35*11K		35.0 (2.13)		70.0 (18.5)	10.7 (1551)	16.0 (2320)		
UPS-2A-25*15K		25.0 (1.52)		50.0 (13.2)	19.1 (2769)	28.7 (4161)		Reservoir:B
UPS-2A-32*15K	15.0 (20.10)	32.0 (1.95)	2000	64.0 (16.9)	15.9 (2305)	23.8 (3451)	B:6.0 (1.58)	V: 2.8 (0.74)
UPS-2A-35*15K		35.0 (2.13)		70.0 (18.5)	15.3 (2218)	23.0 (3335)		H: 0.8 (0.21)
UPS-2A-25*20K		25.0 (1.52)		50.0 (13.2)	25.1 (3639)	30.0 (4350)		
UPS-2A-32*20K	20.0 (26.80)	32.0 (1.95)	2000	64.0 (16.9)	20.9 (3030)	30.0 (4350)		
UPS-2A-35*20K		35.0 (2.13)		70.0 (18.5)	20.2 (2929)	30.0 (4350)		

- (Note 1) Available pressure at maximum rpm is limited due to the characteristics of motor as its torque output lowered during high speed rotation.
- (Note 2) Theoretical flow rate at no load. Actual flow rate may vary by load pressure.
- (Note 3) Rated pressure is the rated torque of motor and the maximum working pressure is at 150% torque which is output capable amount pressure. However, when these pressure types exceed 30MPa, hydraulic unit maximum working pressure will be limited to 30MPa.
- (Note 4) When variable fluid amount is greater than allowable value, additional fluid can be supplied by connecting a secondary tank. Please contact us for more information. (Note 5) When choosing a tankless type, oil tank is required separately. Nachi is available to make one for those customers requesting additional tank. Please contact us for more information.
- (Note 6) Due to operating oil temperature impacted by various factors such as HPU installed environment, operation method and load conditions etc., ensure to check the oil temperature in HPU at working condition. Also, when using HPU under the long continuous pressure loading operation and very frequent cylinder operation, oil temperature gets high which could limit working pressure and/or require additional cooling system installation. Please contact us for more information.
- (Note 7) When mounting an optional circuit, maximum working pressure gets limited as below.
  - · With differential pressure regulating valve (Code: C),

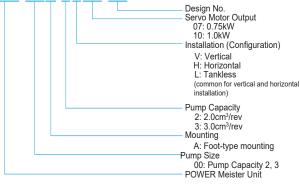
  - UPS-0A, UPS-1A, UPS-2A: Maximum working pressure 25MPa
     With Shut-off Valve (Code: S), UPS-0A, UPS-1A: Maximum working pressure 21MPa

[Precautions at selecting HPU]
Power Meister is the HPU system to drive hydraulic cylinder directly by motor rotations. Torque required for acceleration/deceleration other than motor torque required to create working pressure, feasible maximum flow rate and maximum working pressure could get regulated lower than the MPa listed above. Please ensure about the desirable working cycle and load in HPU (for Power Meister hydraulic cylinder) first and contact us.

#### **Model Code**

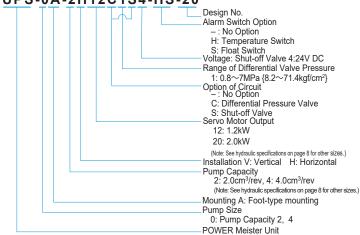
#### **UPS-00A**

#### UPS-00A-2H07-20



#### **UPS-0A**

#### UPS-0A-2H12C1S4-HS-20



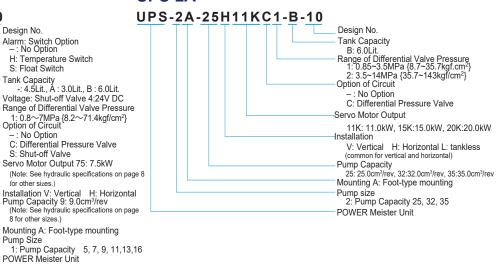
#### **UPS-1A**

#### UPS-1A-9H75C1S4-BHS-20

#### Alarm: Switch Option – : No Option H: Temperature Switch S: Float Switch Tank Capacity -: 4.5Lit., A: 3.0Lit., B: 6.0Lit. Voltage: Shut-off Valve 4:24V DC Range of Differential Valve Pressure 1: 0.8~7MPa {8.2~71.4kgf/cm²} Option of Circuit -: No Option C: Differential Pressure Valve S: Shut-off Valve Servo Motor Output 75: 7.5kW (Note: See hydraulic specifications on page 8 for other sizes.) nstallation V: Vertical H: Horizontal Pump Capacity 9: 9.0cm<sup>3</sup>/rev (Note: See hydraulic specifications on page 8 for other sizes.)

Mounting A: Foot-type mounting

#### **UPS-2A**



Source Volta Consumption		DC24V±15% / 10W maximum	Require separate power supply for sensor
Ambient Ter Humidity	mperature/	0~+55°C (32~131°F) / Under 90% RH	
Control		Control of position, speed and pressure for cylinder	Automatic change function of control mode
Command Pressure Command		Analog voltage DC±10V/Max. cylinder speed (*1) Expand cylinder by + voltage, contract by - voltage	(*1) Set by parameter
		Analog voltage DC±10V/Max. pressure (*2) Pressurize head side by positive voltage, pressurize rod side by negative voltage	(*2) Set by trimmer
	Position Command	Select contact signal to set positions (4 contacts). Select target position by bit pattern of 4 contacts. Controller calculates function of speed for targeted position and maintain.	Set target position, max speed and accelerated/decelerated speed in inside parameter in advance.
Input Signal (Contact Sig		Servo ON, alarm reset, external changeover signal for control mode. Point of origin search start signal, retracion LS and proximity LS from/to point of origin.	
Output Sign	al	Alarm, servo ready, control mode monitor, point of origin search complete/in position (dual output), correspond with pressure	
Pressure Se	ensor Input	Analog voltage 0.5~4.5V or 1~5V (2ch)	Use pressure sensor with responsiveness under 1ms
Position Ser	nsor Input	90° phase difference 2 phase pulse. Point of origin pulse (line receiver input) or analog voltage 0~10V.	If using position sensor for pulse output, point of origin search required after power-up.  Position sensor for pulse output: Under 1µm of resolution.  Position sensor for analog voltage output: Under 2ms responsiveness.
Servo Amplifier Signal I/F		Output: Motor rotation speed command (Analog voltage DC±10V), Servo ON, Servo alarm reset. Input: Servo alarm, servo ready.	
Operation P	anel	5-digit display with code, 4-key input, selector switch.	Data setting, display and trial operation function

- •Connector and pin to connect controller are supplied.
- ●When used spacer for servo controller (Option: FZV-8676-02A-01), set dimension becomes the same as the former design [EPD-PD2-10(-A)-D2-10] and the connector height from the set surface also gets to be almost the same.

### Servo Amplifier Specifications

Hydraulic Unit (UPS)	Motor Output kW (HP)	Corresponding Servo Amplifier Type	Note
UPS-00A-**07	0.75 (1.00)	EPA-PD1-10-R075-20	
UPS-00A-**10	1.0 (1.3)	EPA-PD1-10-R100-20	
UPS-00A-**15	1.5 (2.0)	EPA-PD1-10-R150-20	
UPS-0A-**12	1.2 (1.60)	EPA-PD1-10-R120-20	Built-in regenerative resistor
UPS-0A-**20	2.0 (2.7)	EPA-PD1-10-R200-20	
UPS-1A-***35	3.5 (4.70)	EPA-PD1-10-R350-20	
UPS-1A-***45	4.5 (6.00)	EPA-PD1-10-R450-20	
UPS-1A-***55	5.5 (7.4)	EPA-PD1-10-R550-20	
UPS-1A-***75	7.5 (10.0)	EPA-PD1-10-R750-20	
UPS-1A-***11K	11.0 (14.75 )	EPA-PD1-10-R11K-20	
UPS-2A-***11K	11.0 (14.75)	EPA-PD1-10-SR11K-10	External regenerative resistor
UPS-2A-***15K	15.0 (20.10)	EPA-PD1-10-SR15K-10	
UPS-2A-***20K	20.0 (26.80)	EPA-PD1-10-SR20K-10	Power unit, external regenerative resistor (2pcs) are included

(Note 1) Source: 3 phase AC200~230V 50/60Hz

(Note 2) Separate motor cable and encoder cables required to connect the servo motor of hydraulic unit and servo amplifier.

(Note 3) An auxiliary external regenerative resistor may be required in some operating conditions if the built-in or external regenerative resistor is not sufficient. Contact NACHI for more details about your operating conditions.

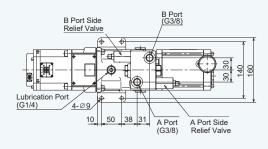
(Note 4) Connector for wire connection supplied.

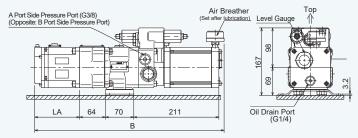
#### **Set Diemnsions**

#### UPS-00A Series

#### **UPS-00A-\*H\*\*\*\*** (Horizontal Type)

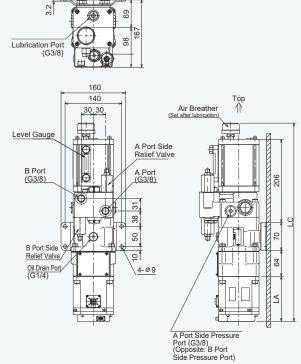
#### UPS-00A-\*V\*\*\*\* (Vertical Type)

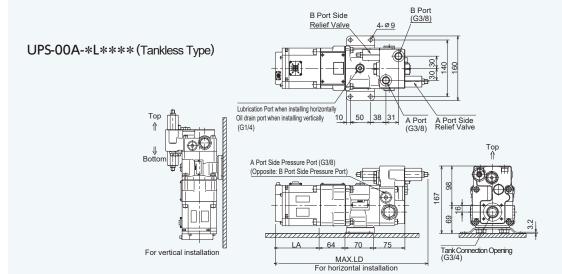




UPS Model	LA	LB	LC	Weight
UPS-00A-* H 07	111 (4.37)	469 (18.46)	491 (19.33)	16kg (35.3)
UPS-00A-* H10	128 (5.04)	486 (19.13)	508 (20.00)	17kg(37.5)

(Note 1) Air breather is included in a package. Once oil tank is filled, please install it on your own. (Note 2) Unit needs to be installed at designated installation position. (H: horizontal installation, V: Vertical installation

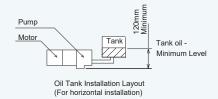




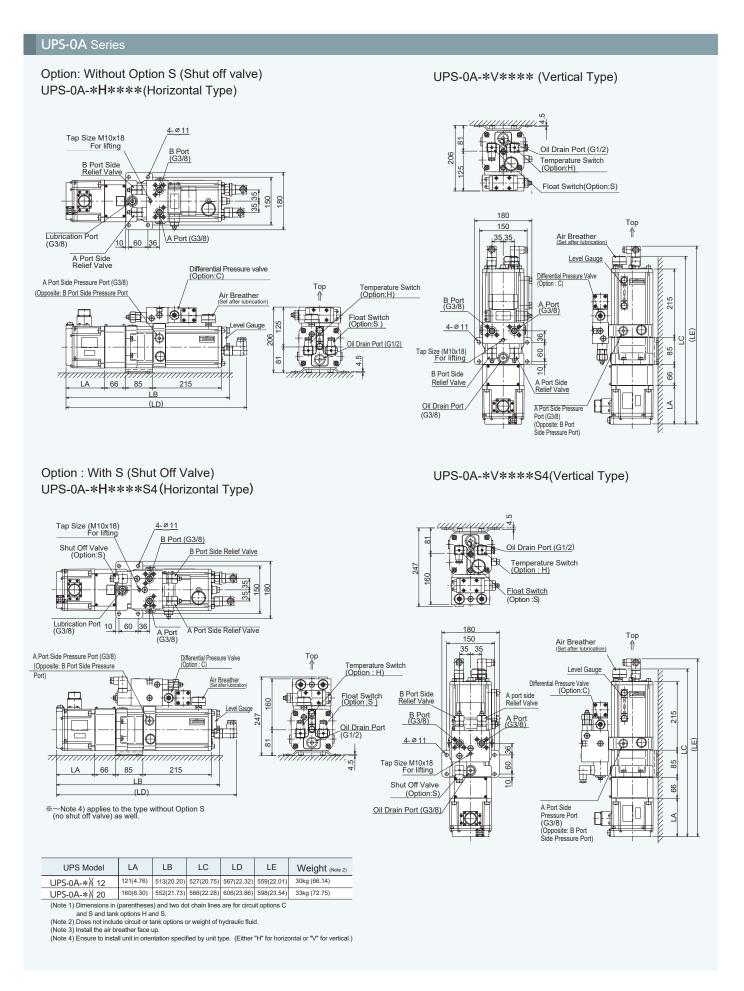
UPS Model	LA	LD	Weight
UPS-00A-*L07	111 (4.37)	377 (14.84)	14 kg(30.86)
UPS-00A-*L10	128 (5.04)	394 (15.51)	15kg (33.06)

(Note 1) Oil tank required separately. Nachi is available for production. Please consult with us if you need one. (Note 2) Please install either horizontally or vertically. And when installing vertically, ensure to have the servo motor facing the bottom.

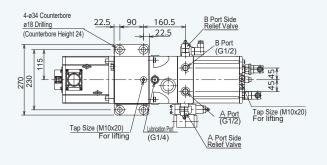
(Note 3) when installing horizontally, the oil tank position to be 120mm or more of the oil minimum level of the bottom surface during cylinder operation. (See diagram on the right for oil tank installation layout.)

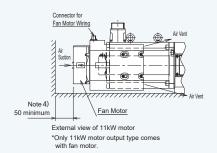


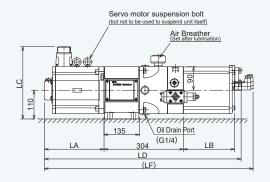
#### **Set Dimension**

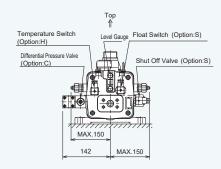


#### UPS-1A-\*\*H\*\*\*\* (Horizontal Type)

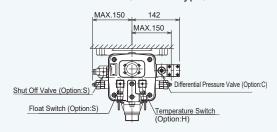








#### UPS-1A-\*\*V\*\*\*\* (Vertical Type)



UPS Model	LA	LB	LC	LD	LE	LF	LG	Weight Note 2)
UPS-1A-** H35****-A		120		608	627	654	645	60kg
UPS-1A-** H35****	159	195	254	683	702	729	720	61kg
UPS-1A-** H35****B	1	275	]	763	782	809	800	63kg
UPS-1A-** H45****-A		120		625	644	671	662	64kg
UPS-1A-** H45****	176	195	254	700	719	746	737	65kg
UPS-1A-** H45****-B		275		780	799	826	817	67kg
UPS-1A-** H55****-A		120		677	696	723	714	70kg
UPS-1A-** H55****	228	195	276	752	771	798	789	71kg
UPS-1A-** H55****-B		275		832	851	878	869	73kg
UPS-1A-** H75****-A		120		722	741	768	759	78kg
UPS-1A-** H75****	273	195	276	797	816	843	834	79kg
UPS-1A-** H75****B	1	275	]	877	896	923	914	81kg
UPS-1 A - * * H 11K****-A		120		844	863	890	881	85kg
UPS-1A-** H11K****	395	195	276	919	938	965	956	86kg
UPS-1 A - * * H 11K****-B	1	275	1	999	1018	1045	1036	88kg

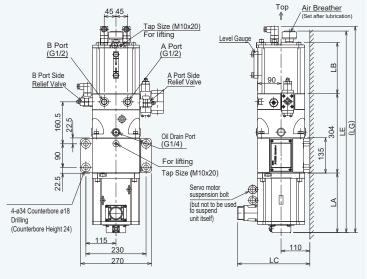
(Note-1) Reference dimension and chain double-dashed line indicate outer dimension of circuit option "C", "S" and the unit type with alarm switch option "H", "S".

(Note 2) Does not include circuit or tank options or weight of hydraulic fluid.

(Note 3) Install the air breather face up.

(Note-4) Only motor output 11kW type comes with fan motor. Apply minimum 50mm space for fan motor air suction.

(Note-5) Ensure to install unit in orientation specified by unit type. (Either "H" for horizontal or "V" for vertical.)

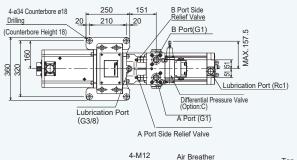


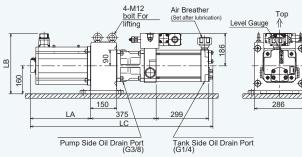
#### **Set Dimensions**

#### **UPS-2A** Series

#### UPS-2A-\*\*H\*\*\*\*(Horizontal Type)

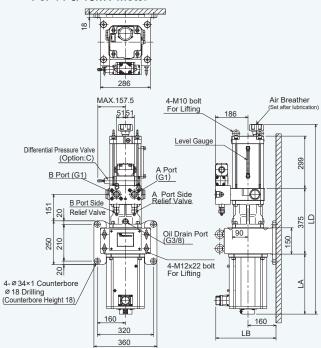
#### For 11 & 15kW Motor



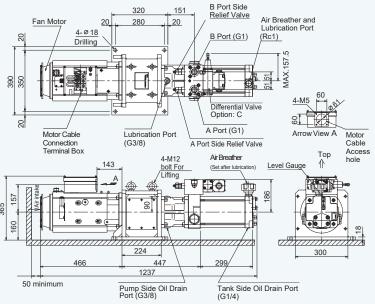


#### UPS-2A-\*\*V\*\*\*\*(Vertical Type)

#### For 11 & 15kW Motor



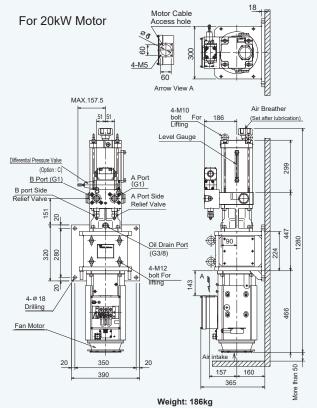
## For 20kW Motor





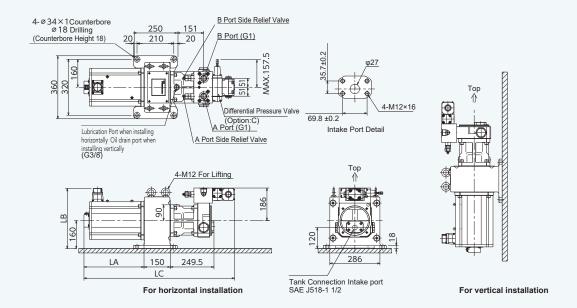
UPS Model	LA	LB	LC	LD	Weight			
UPS-2A-**H11K**-B	304	344	1003	-	156kg			
UPS-2A-**V11K**-B	304	344	-	1046	156kg			
UPS-2A-**H15K**-B	343	344	1042	-	163kg			
UPS-2A-**V15K**-B 343 344 - 1085 163kg								
(Note 1) Air breather is included in	a package. (	Once oil tank	is filled, pleas	e install it on	vour own.			

(Note 2) Fan motor comes with the unit for only 20kW motor. When installing the unit, please allow more than 50mm space for fan air intake (Note 3) Unit needs to be installed at designated installation position. (H: horizontal installation, V: vertical installation)

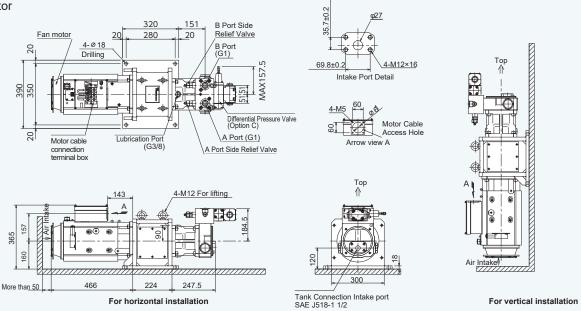


#### UPS-2A-\*\*L\*\*\*\*(Tankless)

#### For 11 & 15kW Motor





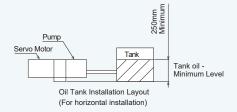


Weight: 176kg

UPS Model	LA	LB	LC	Weight
UPS-2A-**L11K**	304	344	822	146kg
UPS-2A-**L15K**	343	344	861	153kg

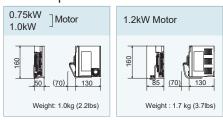
(Note 1) Oil tank required separately. Nachi is available for production. Please consult with us if you need one (Note 2) Please install either horizontally or vertically. And when installing vertically, ensure to have the servo motor facing the bottom.

(Note 3) when installing horizontally, the oil tank position to be 250 mm or more of the oil minimum level of the bottom surface during cylinder operation. (See diagram on the right for oil tank installation layout.)



#### **Set Dimension Diagram**

#### Servo Amplifier



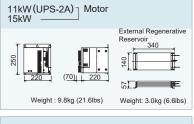


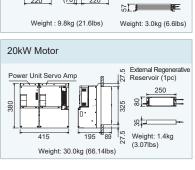
Motor

24

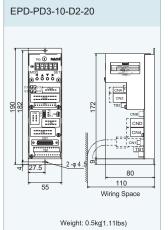
Weight: 9.6kg (21.2lbs) Weight: 3.0kg (6.6lbs)

External Regenerative



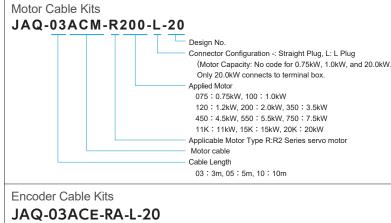


#### Servo Controller



#### **Cable Kit Specifications**

Weight: 5.3kg (11.7lbs)



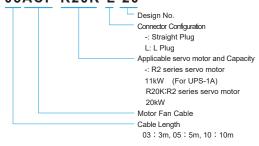
7 5kW

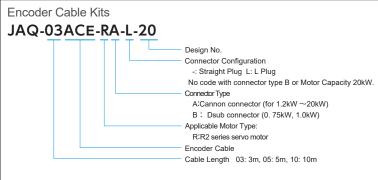
11kW (UPS-1A)

220

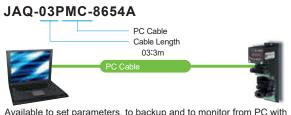
(70) 220







#### PC Cable Kits



Available to set parameters, to backup and to monitor from PC with use of PC cable kits.

\*Utility software can be used in common for bot EPD-PD2-10(-A)-D2-10 and EPD-PD3-10-D2-20.

#### Warning



- Drastic acceleration during operation may shorten the life of hydraulic unit. When abnormal noise such as impact noise occurs from HPU, it indicates that an intensive torque had occurred. Please review your operation command and/or limit servo amp torque.
- ■When depressurizing HPU by reverse of servo motor, ensure to release pressure slowly to avoid sudden torque change. When shorter pressure release time required, another method such as additional depressurizing circuit (valve exclusive for pressure release) available to install.
- ■The safety valve installed in HPU is to protect hydraulic circuit protection in the event of emergency. Safety valve should never be activated during regular operation. Please ensure to adjust and regulate your set pressure to avoid this valve activation. When safety valve gets activated, fluid temperature will rapidly raise and cause issues.



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